AN ADAPTABLE ELLIPSOIDAL HEAD MODEL FOR THE INTERAURAL TIME DIFFERENCE

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ABSTRACT
Experimentally measured head-related transfer functions reveal that the interaural time delay varies from person to person. Furthermore, it is not constant around a cone of confusion, but can vary by as much as 18% of the maximum interaural delay. The major sources for this variation are shown to be the shape of the head and the displacement of the ears from the center of the head. A simple ellipsoidal head model is presented that can accurately account for this ITD variation and can be adapted to individual listeners.

1. INTRODUCTION
Models of head-related transfer functions (HRTF’s) are becoming widely used in spatial audio systems [1, 2]. We are currently developing structural HRTF models, whose parameters are directly related to the size and shape of the listener’s torso, head and outer ears [3]. This enables the customization of a generic model to an individualized HRTF through simple anthropometric measurements.

The Interaural Time Difference (ITD) provides the major cue for azimuth localization, and is a core part of any HRTF model. If the head is approximated by a sphere of radius $a$, the ITD for an infinitely distant source can be computed by a simple formula due to Woodworth [4]:

$$\text{ITD} = \frac{a}{c} (\theta + \sin \theta)$$  \hspace{1cm} (1)

where $\theta$ is the azimuth angle and $c$ is the speed of sound. Derived from a simple ray-tracing argument, this formula is restricted to angular frequencies greater than $a/c$, and corresponds to the difference in first arrival times. However, it is remarkably close to the exact theoretical solution, even for a source that is quite near the sphere [5]. Furthermore, customization requires the measurement of only one quantity, the average head radius.

It follows from (1) that a surface of constant ITD is a cone of revolution about the interaural axis. Woodworth called this surface the “cone of confusion.” For an ideal spherical head, neither the ITD nor the ILD (Interaural Level Difference) changes as a point is moved around a cone of confusion. Since the ITD and the ILD are primary cues for source localization, this provides a simple explanation of the fact that many localization errors (including front/back errors and up/down errors) result in mislocation on the cone of confusion.

However, a sphere provides only a first approximation to a real human head. We will present experimental results that show that in reality the ITD varies around a cone of confusion, so that the ITD is a function of elevation as well as azimuth.\footnote{This work was supported by the National Science Foundation under Grant No. IRI-9619339. Any opinions, findings, and conclusions or recommendations expressed in this paper are those of the authors and do not necessarily reflect the views of the National Science Foundation.}

1 This elevation dependence arises because, although the distance from the source to the ipsilateral ear (the ear that is visible from the source) is constant, the length of the shortest path from the source to the contralateral ear (the ear that is not visible from the source) changes with elevation. These changes are due both to the non-spherical shape of the head and to the fact that the ears are not positioned across a diameter, but are displaced behind and below the center of the head. We will show how a simple ellipsoidal model with offset ears yields the proper variation of ITD with both azimuth and elevation.

2. HRTF DATA
The ITD is directly revealed in experimentally measured impulse response data. Fig. 1 shows an image representa-
A sound source with these impulse responses, the sound image appears to move smoothly in a vertical plane parallel to the median plane as the elevation is slowly changed from $-50^\circ$ to $230^\circ$. However, if the responses of the contralateral ear are time aligned and then delayed by a constant ITD, the sound image is not confined to a vertical plane, but appears to be significantly displaced to the right and left as the source moves around the cone. In short, for accurate placement of the virtual source, Woodworth’s formula is inadequate, and the formula used to compute the ITD must be a function of elevation as well as azimuth.

A closer examination of the contralateral image reveals a “bright spot” near $90^\circ$ elevation. This can be explained using an elementary multipath interpretation. At $-55^\circ$ azimuth, the shortest path from the source to the contralateral ear is around the front of the head if the source is in front, and around the back of the head if the source is in back. Normally, one of these two paths dominates. However, near $90^\circ$ elevation, these paths have the same length, and the signals arrive in phase to produce the bright spot. Indeed, with just a little imagination, one can discern the separate components around the front and around the back in the contralateral image (Fig. 1b).

3. THE ELLIPSOIDAL HEAD MODEL

Although this shortest-path argument is an oversimplification and cannot explain all the behavior of what is clearly a complex wave propagation phenomenon, it is similar to Woodworth’s original argument, and it leads to a surprisingly accurate model for computing the ITD. In particular, the variation in the ITD with elevation is easily explained by observing that if the shape of the head is not spherical, and/or if the ears are not located across a diameter, then the length of the shortest path from the source to the contralateral ear will vary with elevation.

An ellipsoid is an obvious choice for a head model that exhibits elevation as well as azimuth dependence. To express the model analytically, let $\tilde{s} = [s_1, s_2, s_3]^T$ be a vector from the origin to the sound source, and let $\tilde{e} = [e_1, e_2, e_3]^T$ be a similar vector to the contralateral ear. Define the ellipsoid by the equation

$$\langle \hat{x} - \hat{x}_0 \rangle^T A (\hat{x} - \hat{x}_0) = 1$$  \hspace{1cm} (2)

where $\hat{x} = [x_1, x_2, x_3]^T$ is a vector to a point on the ellipsoid, $\hat{x}_0$ is the center of the ellipsoid, and $A$ is a $3 \times 3$ positive definite, symmetric matrix. Typically, $A = $ 

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2To the best of our knowledge, the only analytic, non-spherical head models that have been investigated are prolate spheroids, and this prior work did not address the ITD [6, 7].

3We assume that all vectors are column vectors, and we denote the transpose of $\hat{x}$ by $\hat{x}^T$. 

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2. Find the point $\vec{e}_p$ where the line from $\vec{s}$ to $\vec{e}$ pierces $P_t$.

3. Find $\vec{t}$ by assuming that it is the point on the tangent ellipse that is closest to $\vec{e}_p$.

4. Find the plane $P_b$ passing through $\vec{s}$, $\vec{t}$, and $\vec{e}$.

5. Compute $d_1$ as the straight-line distance from $\vec{s}$ to $\vec{t}$, and $d_2$ as the arc length from $\vec{t}$ to $\vec{e}$ of the ellipse that results from intersecting the ellipsoid with $P_b$.

It turns out that the equation for $P_t$ is $\vec{n}^T(\vec{x} - \vec{x}_0) = 1$, where $\vec{n} = A(\vec{s} - \vec{x}_0)$, and that $\vec{e}_p = \vec{e} - \lambda(\vec{s} - \vec{e})$, where $\lambda = \frac{1 - \vec{n}^T(\vec{e} - \vec{x}_0)}{\vec{n}^T(\vec{s} - \vec{e})}$. Finding $\vec{t}$ requires minimizing $||\vec{x} - \vec{e}_p||^2$ subject to the constraints $(\vec{x} - \vec{x}_0)^T A(\vec{x} - \vec{x}_0) = 1$ and $\vec{n}^T(\vec{x} - \vec{x}_0) = 1$. Although an analytical solution exists, it is sufficiently complicated that we solved this problem by numerical computation. Once $\vec{t}$ is found, the remaining steps are straightforward.

4. EXPERIMENTAL RESULTS

To apply this procedure, we need to have numerical values for the five parameters. One approach is to imagine enclosing the head in a rectangular box, to use the dimensions of the box for $a_1, a_2$, and $a_3$, and to measure $e_0$ and $e_d$ from the center of the box. While this produces results that are qualitatively better than the spherical-model formula (1), we discovered that the resulting calculated ITD values tended to underestimate the measured ITD. Significantly better results were obtained when the head dimensions were increased by 5 to 10%.

An LMS procedure was used to optimize the model parameter values. The ITD computed by this method is shown in Fig. 4 as the curved white line superimposed on the image for the contralateral ear. Since the azimuth is constant, the spherical model yields the straight black line. The dotted points in Fig. 4 show the empirical ITD, defined as the difference in first arrival times for the two ears, where the first arrival time is the time at which the impulse response first exceeds 15% of the maximum absolute value of the response. Clearly, the ellipsoidal model, which has an average absolute error of 10 µs, fits the data better than the spherical model, which has an average absolute error of 30 µs.4

This is typical of the results obtained at different azimuth angles and with different subjects. Fig. 5 shows the results obtained for the same subject at 25 azimuths and 50 elevations. In this case, the average absolute ITD error is 15 µs for the ellipsoidal model versus 22 µs for the spherical model, which is a relatively small difference. However,

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4 The time between samples at the standard 44.1-kHz sampling rate is 22.7 µs. While a 1.3-sample error might seem small, it introduces a clearly audible shift in location.
because the ITD for the spherical model does not depend on elevation, the spherical model introduces a systematic error that is revealed by the horizontal streaks in the data. Clearly, the ellipsoidal model removes this systematic error, and provides generally superior results at large azimuths.

5. CONCLUSIONS

A simple ellipsoidal model of the head that includes downward and backward displacements of the ears can provide accurate values for the ITD for an HRTF model. By contrast with a spherical head model, the resulting ITD’s vary around a cone of confusion, and provide the proper time delays needed for precise localization. The correction is most important at larger azimuths, where the elevation dependence of the ITD is strongest.

The ellipsoidal head model requires five parameter values, all of which are related to anthropometric measurements of the listener’s head. Although experiments with more subjects will be needed to determine the exact nature of this relationship, our results demonstrate the feasibility of using geometrical models in an important part of a customizable HRTF model.

6. REFERENCES


